## Product data sheet

Characteristics

## ATV212HD22N4

variable speed drive ATV212-22kW - 30hp 480V - 3ph - EMC - IP21


| Main |  |
| :--- | :--- |
| Range of product <br> Product or component <br> type | Altivar 212 |
| Device short name | ATV212 |
| Product destination | Asynchronous motors |
| Product specific appli- <br> cation | Pumps and fans in HVAC |
| Assembly style | With heat sink |
| Network number of <br> phases | 3 phases |
| Motor power kW | 22 kW |
| Motor power hp | 30 hp |
| Power supply voltage | $380 \ldots .480 \mathrm{~V} \mathrm{(-15} \mathrm{\ldots ..10} \mathrm{\%)}$ |
| Power supply voltage <br> limits | $323 \ldots . .528 \mathrm{~V}$ |
| Supply frequency | $50 \ldots 60 \mathrm{~Hz} \mathrm{(-5...5} \mathrm{\%)}$ |
| Network frequency | $47.5 \ldots 63 \mathrm{~Hz}$ |
| EMC filter | $\mathrm{Class} \mathrm{C2EMC} \mathrm{filter} \mathrm{integrated}$ |
| Line current | 41.6 A for 380 V |



| Tightening torque | $\begin{aligned} & 24 \text { N.m - } 212 \text { Ib.in (L1/R, L2/S, L3/T) } \\ & 0.6 \text { N.m (VIA, VIB, FM, FLA, FLB, FLC, RY, RC, F, R, RES) } \end{aligned}$ |
| :---: | :---: |
| Supply | Internal supply: $24 \mathrm{~V}(21 \ldots 27 \mathrm{~V}) \mathrm{DC}-<=200 \mathrm{~A}$ with overload and short-circuit protection <br> Internal supply for reference potentiometer ( 1 to 10 kOhm): 10.5 V DC, $+/-5$ \% <= 10 A with overload and short-circuit protection |
| Analogue input number | 2 |
| Analogue input type | Configurable voltage: (VIB) 0... 10 V DC - 24 V max - 30000 Ohm - resolution: 10 bits <br> Switch-configurable current: (VIA) $0 \ldots . .20 \mathrm{~mA}-250$ Ohm - resolution: 10 bits <br> Switch-configurable voltage: (VIA) 0... 10 V DC - 24 V max - 30000 Ohm - resolution: 10 bits <br> Configurable PTC probe: (VIB) 0... 6 probes -1500 Ohm |
| Sampling duration | $\begin{aligned} & 22 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (VIB) - analog input(s) } \\ & 3.5 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (VIA) - analog input(s) } \\ & 2 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (RES) - discrete input(s) } \\ & 2 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (R) - discrete input(s) } \\ & 2 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (F) - discrete input(s) } \end{aligned}$ |
| Response time | ```7 ms +/- 0.5 ms (RY, RC) - discrete output(s) 7 ms +/- 0.5 ms (FLB, FLC) - discrete output(s) 7 ms +/- 0.5 ms (FLA, FLC) - discrete output(s) 2 ms +/- 0.5 ms (FM) - analog output(s)``` |
| Accuracy | +/- $1 \%$ (FM) for a temperature variation $60^{\circ} \mathrm{C}$ <br> $+/-0.6$ \% (VIB) for a temperature variation $60^{\circ} \mathrm{C}$ <br> $+/-0.6 \%$ (VIA) for a temperature variation $60^{\circ} \mathrm{C}$ |
| Linearity error | $\begin{aligned} & +/-0.2 \% \text { for output (FM) } \\ & \text { +/- } 0.15 \% \text { of maximum value for input (VIB) } \\ & \text { +/- } 0.15 \% \text { of maximum value for input (VIA) } \end{aligned}$ |
| Analogue output number | 1 |
| Analogue output type | Switch-configurable current: (FM) $0 . . .20 \mathrm{~mA}-970$ Ohm - resolution: 10 bits Switch-configurable voltage: (FM) 0... 10 V DC - 7620 Ohm - resolution: 10 bits |
| Discrete output number | 2 |
| Discrete output type | Configurable relay logic: (RY, RC) NO - 100000 cycles Configurable relay logic: (FLB, FLC) NC - 100000 cycles Configurable relay logic: (FLA, FLC) NO - 100000 cycles |
| Minimum switching current | 3 mA at 24 V DC (configurable relay logic) |
| Maximum switching current | 2 A at 30 V DC on inductive load $-\cos$ phi $=0.4-\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}$ (FL, R) 2 A at 250 V AC on inductive load $-\cos \mathrm{phi}=0.4-\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}(F L, R)$ 5 A at 30 V DC on resistive load $-\cos \mathrm{phi}=1-\mathrm{L} / \mathrm{R}=0 \mathrm{~ms}$ (FL, R) 5 A at 250 VAC on resistive load $-\cos$ phi $=1-\mathrm{L} / \mathrm{R}=0 \mathrm{~ms}(\mathrm{FL}, \mathrm{R})$ |
| Discrete input type | Programmable (RES) 24 V DC, with level 1 PLC - 4700 Ohm Programmable (R) 24 V DC, with level 1 PLC - 4700 Ohm Programmable (F) 24 V DC, with level 1 PLC - 4700 Ohm |
| Discrete input logic | Negative logic (sink) (F, R, RES), >= 16 V (state 0 ), <= 10 V (state 1 ) Positive logic (source) (F, R, RES), <=5 V (state 0), >= 11 V (state 1) |
| Acceleration and deceleration ramps | Automatic based on the load Linear adjustable separately from 0.01 to 3200 s |
| Braking to standstill | By DC injection |
| Protection type | With PTC probes for motor Motor phase break for motor Thermal protection for motor Against input phase loss for drive Line supply undervoltage for drive Line supply overvoltage and undervoltage for drive Against exceeding limit speed for drive Break on the control circuit for drive Overvoltages on the DC bus for drive Overcurrent between output phases and earth for drive Input phase breaks for drive Short-circuit between motor phases for drive Thermal power stage for drive Overheating protection for drive |
| Dielectric strength | 5092 V DC between control and power terminals 3535 V DC between earth and power terminals |
| Insulation resistance | >= 1 MOhm at 500 V DC for 1 minute |
| Frequency resolution | $0.024 / 50 \mathrm{~Hz}$ for analog input 0.1 Hz for display unit |


| Communication port protocol | APOGEE FLN <br> BACnet <br> LonWorks |
| :--- | :--- |
|  | METASYS N2 <br> Modbus |
| Connector type | 1 RJ45 |
|  | 1 open style |
| Physical interface | 2 -wire RS 485 |
| Transmission frame | RTU |
| Transmission rate | 9600 bps or 19200 bps |
| Data format | 8 bits, 1 stop, odd even or no configurable parity |
| Type of polarization | No impedance |
| Number of addresses | $1 \ldots 247$ |
| Communication service | Monitoring inhibitable |
|  | Read device identification (43) |
|  | Read holding registers (03) 2 words maximum |
| Time out setting from 0.1 to 100 s |  |
| Write multiple registers (16) 2 words maximum |  |
| Option card | Write single register (06) |
| Width | Communication card for LonWorks |
| Height | Vertical +/- 10 degree |
| Depth | 240 mm |
| Product weight | 420 mm |
| Fower dissipation in W flow rate | 214 mm |

## Environment

| Electromagnetic compatibility | Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 <br> Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 |
| :--- | :--- |
|  | $1.2 / 50 \mu \mathrm{~s}-8 / 20 \mu$ surge immunity test level 3 IEC $61000-4-5$ |
|  | Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 <br> Radiated radio-frequency electromagnetic field immunity test level 3 conforming <br> to IEC $61000-4-3$ |
|  | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 |


| Standards | EN 55011 class A group 1 |
| :--- | :--- |
|  | EN 61800-3 |
|  | EN 61800-3 category C2 |
|  | EN 61800-3 category C3 |
|  | EN 61800-3 environments 1 category C1 |
|  | EN 61800-3 environments 1 category C2 |
|  | EN 61800-3 environments 1 category C3 |
|  | EN 61800-3 environments 2 category C1 |
|  | EN 61800-3 environments 2 category C2 |
|  | EN 61800-3 environments 2 category C3 |
|  | EN 61800-5-1 |
|  | IEC 61800-3 |
|  | IEC 61800-3 category C2 |
|  | IEC 61800-3 category C3 |
|  | IEC 61800-3 environments 1 category C1 |
|  | IEC 61800-3 environments 1 category C2 |
|  | IEC 61800-3 environments 1 category C3 |
|  | IEC 61800-3 environments 2 category C1 |
|  | IEC 61800-3 environments 2 category C2 |
|  | IEC 61800-3 environments 2 category C3 |
|  | IEC 61800-5-1 |
|  | UL Type 1 |
| Product certifications | CSA |
|  | C-Tick |
|  | NOM 117 |
| Marking | UL |

Offer Sustainability

| Sustainable offer status | Not Green Premium product |
| :--- | :--- |
| RoHS | Compliant - since $1050-$ Schneider Electric declaration of conformity <br> declaration of conformity |
| Product end of life instruction | Available 园 Download End Of Life Manual |

## Product data sheet

## ATV212HD22N4

## Dimensions Drawings



Dimensions in mm

| ATV212H | a | b | c | G | H | K | $\varnothing$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| D22M3X <br> D22N4, D30N4 | 240 | 420 | 214 | 206 | 403 | 10 | 6 |
| D37N4, D45N4 | 240 | 550 | 244 | 206 | 529 | 10 | 6 |

Dimensions in in.

| ATV212H | a | b | c | G | H | K | Ø |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| D22M3X <br> D22N4, D30N4 | 9.45 | 16.54 | 8.43 | 8.11 | 15.87 | 0.39 | 0.24 |
| D37N4, D45N4 | 9.45 | 21.65 | 9.60 | 8.11 | 20.83 | 0.39 | 0.24 |

EMC mounting plate (supplied with drive)


Dimensions in mm

| ATV212H | b1 | c1 |
| :--- | :--- | :--- |
| D22M3X <br> D22N4, D30N4 | 122 | 120 |
| D37N4, D45N4 | 113 | 127 |

Dimensions in in.

| ATV212H | b1 | c1 |
| :--- | :--- | :--- |
| D22M3X <br> D22N4, D30N4 | 4.80 | 4.72 |
| D37N4, D45N4 | 4.45 | 5.00 |

## Clearance

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.
Install the unit vertically:

- Do not place it close to heating elements.
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from bottom to the top of the unit. $\frac{\mathrm{mm}}{\mathrm{in} .}$



## Mounting Types

Type A mounting
mm


Type B mounting


Type C mounting
$\frac{\mathrm{mm}}{\mathrm{in} .}$


By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP21. The protective blanking cover may vary according to the drive model, see opposite.

Specific Recommendations for Mounting in an Enclosure

To help ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Check that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).

- Use special filters with UL Type 12/IP54 protection.
- Remove the blanking cover from the top of the drive.


## Sealed Metal Enclosure (IP54 Degree of Protection)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions, such as dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. This enables the drive to be used in an enclosure where the maximum internal temperature reaches $50^{\circ} \mathrm{C}$.

## 3-Phase Power Supply



A1: ATV 212 drive
KM1: Contactor
Q1: Circuit breaker
Q2: GV2 L rated at twice the nominal primary current of T1
Q3: GB2CB05
S1, XB4 B or XB5 A pushbuttons
S2:
T1: 100 VA transformer 220 V secondary
(1) Fault relay contacts for remote signalling of the drive status
(2) Connection of the common for the logic inputs depends on the positioning of the switch (Source, PLC, Sink)
(3) Reference potentiometer SZ1RV1202

All terminals are located at the bottom of the drive. Install interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

## Switches (Factory Settings)

Voltage/current selection for analog I/O (VIA and VIB)


Voltage/current selection for analog I/O (FM)


Selection of logic type

(1) negative logic
(2) positive logic

## Logic Inputs According to the Position of the Logic Type Switch

"Source" position

"Sink" position

"PLC" position with PLC transistor outputs
(1) PLC ATV

2-wire control


F: Forward
R: Preset speed
(2) ATV 212 control terminals

3-wire control


F: Forward
R: Stop
RES: Reverse
(2) ATV 212 control terminals

PTC probe

(2) ATV 212 control terminals
(3) Motor

## Analog Inputs

Voltage analog inputs
External +10 V

(2) ATV 212 control terminals
(4) Speed reference potentiometer 2.2 to $10 \mathrm{k} \Omega$

(2) ATV 212 control terminals

Analog input configured for current: 0-20 mA, 4-20 mA, X-Y mA

(2) ATV 212 control terminals
(5) Source 0-20 mA, 4-20 mA, X-Y mA

Analog input VIA configured as positive logic input ("Source" position)

(2) ATV 212 control terminals

Analog input VIA configured as negative logic input ("Sink" position)

(2) ATV 212 control terminals

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type (A, B or C). For intermediate temperatures ( $45^{\circ} \mathrm{C}$ for example), interpolate between 2 curves.


X Switching frequency

